

METHOD FOR OPERATING A PLL FREQUENCY SYNTHESIS CIRCUIT

5 Cross-Reference to Related Application:

This application is a continuation of copending International Application No. PCT/DE02/00171, filed January 21, 2002, which designated the United States and was not published in English.

10 Background of the Invention:

Field of the Invention:

The invention relates to a method for operating a PLL frequency synthesis circuit for a TDMA/FDMA data transmission device.

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Time division multiple access (TDMA) methods and frequency division multiple access (FDMA) methods are multiple access methods that are used in a large number of data transmission systems (cordless telephony, data interchange between

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computers and peripherals, etc.). TDMA is based on the subdivision of the time into time slots, which are then used for interchanging data in portions between terminals (for example base stations and mobile stations). FDMA is analogous to TDMA in the frequency domain, that is to say it relates to

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the subdivision of the overall transmission bandwidth into

individual user channels, which are available to two or more users for simultaneous data transmission.

Frequency hopping (FH) methods, are characterized in that the transmission frequency (that is to say the user channel) for each transmitter is changed continually during transmission operation. FH decreases the interference susceptibility because it guarantees that transmission only ever takes place for a short time via individual channels that are subject to severe interference, and can therefore be kept within certain limits.

A phase locked loop (PLL) frequency synthesizer is used to produce the transmission frequency in data transmission systems. A certain amount of time is required for the frequency changes that are required for the FH method, owing to the stabilization processes in the PLL. This time is referred to in the following text as the settle time. Since the settle time cannot be used for data transmission, it should be kept as short as possible.

The normal method for shortening the settle time in the PLL is to widen the transmission bandwidth of the PLL. This has the disadvantage that the noise response of the PLL becomes worse. Phase locked loops with short settle times and low noise are

relatively complex, and cannot be used for many applications,  
for cost reasons.

One known method for operating a PLL frequency synthesizer for  
5 a frequency change is to deactivate the PLL for the frequency  
synthesizer after transmitting the last transmitted data burst  
or data packet. This is done by switching off the voltage  
controlled oscillator for the PLL. The PLL frequency  
synthesizer is then set to the next desired frequency value,  
10 and is activated once again for transmission of the next data  
burst. The next data burst is transmitted after the  
stabilization process.

Published, Non-Prosecuted German Application DE 197 36 463 A1,  
15 which represents the closest prior art, describes a method for  
operating a phase locked loop, in which the phase locked loop  
is deactivated in a time period without transmission activity.  
This procedure is also addressed in Published, Non-Prosecuted  
German Application DE 197 36 464 A1.

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Published, Non-Prosecuted German Application DE 196 11 219 A1  
describes a phase locked loop with a loop filter having a  
switchable loop bandwidth. Switching the loop bandwidth  
shortens the time interval that is required for a  
25 stabilization process between two transmission processes.

Summary of the Invention:

It is accordingly an object of the invention to provide a method for operating a PLL frequency synthesis circuit that overcomes the above-mentioned disadvantages of the prior art methods of this general type, which allows short settle times for the PLL frequency synthesis circuit during frequency changing.

With the foregoing and other objects in view there is provided, in accordance with the invention, a method for operating a PLL frequency synthesis circuit for a TDMA/FDMA data transmission device. The method includes operating the PLL frequency synthesis circuit in an active state for transmitting data during a first period using a first output frequency synthesized by the PLL frequency synthesis circuit. No data transmission activity is carried out by the TDMA/FDMA data transmission device during an intermediate period following the first period. The PLL frequency synthesis circuit is reprogrammed from the first output frequency to a stabilization basic frequency, located in a suitable manner in a usable frequency band, after the first period has elapsed from which a stabilization process to a second output frequency is carried out. The PLL frequency synthesis circuit is operated for transmitting further data during a second period using the second output frequency, not being equivalent to the first output frequency, following the intermediate

period, the PLL frequency synthesis circuit synthesizing the second output frequency.

Accordingly, the idea on which the invention is based is for  
5 the PLL frequency synthesis circuit not to be deactivated during a frequency change, but to be kept in the active state and for the stabilization process to be carried out from the active state to the next output frequency. Provision is in this case made for the PLL frequency synthesis circuit to be  
10 reprogrammed, after the first period of data transmission activity has ended, to a stabilization basic frequency, which is located in a suitable manner in the usable frequency band, and then to be changed from the stabilization basic frequency to the second output frequency.

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Stabilization processes admittedly also occur here; however, owing to the comparatively narrow bandwidth of the usable frequency band, these are shorter than in the case of conventional methods and - as will be explained in the  
20 following text - are less influenced by production tolerances.

The method according to the invention is particularly advantageous when the next output frequency is not yet known after the first period with data transmission activity has  
25 ended.

Since the mid-frequency of the frequency band that is used for FDMA operation is chosen for the stabilization basic frequency, this results in that the greatest sudden frequency change that need be expected is minimal. Since the settle  
5 time that is required for the frequency change increases with the separation between the stabilization basic frequency and the second output frequency, this results in that it is possible to specify an upper limit with a minimum size for the settle time with respect to all the possible frequency changes  
10 in the FDMA frequency band.

One particular advantage is achieved by the method according to the invention if the data transmission is based on a TDMA structure in which the start of a specific time slot coincides  
15 with the start of the first data transmission period, and the start of the next time slot coincides with the start of the second data transmission period, and with the time period between the end of the first data transmission period and the start of the second data transmission period being shorter  
20 than that settle time of the PLL frequency synthesis circuit which would occur if the PLL frequency synthesis circuit were to be controlled from the deactivated state to the second output frequency. In this situation, the procedure according to the invention results in that a frequency change is still  
25 possible in the remaining time period of the time slot under consideration while, in the case of a conventional method, the

frequency change must be carried out at a later time. In practice, for example in the case of digital European cordless telecommunications (DECT) systems, a dedicated time slot with a duration of 416 us is frequently used for the frequency  
5 change, particularly because this makes it possible to use lower-cost PLLs with longer settle times. The method according to the invention for operating a PLL frequency synthesis circuit may make it possible to once again save this additionally required time slot.

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In accordance with an added mode of the invention, there is the step of transmitting the data using a Bluetooth standard or the DECT standard.

15 Other features which are considered as characteristic for the invention are set forth in the appended claims.

Although the invention is illustrated and described herein as embodied in a method for operating a PLL frequency synthesis  
20 circuit, it is nevertheless not intended to be limited to the details shown, since various modifications and structural changes may be made therein without departing from the spirit of the invention and within the scope and range of equivalents of the claims.

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The construction and method of operation of the invention, however, together with additional objects and advantages thereof will be best understood from the following description of specific embodiments when read in connection with the accompanying drawings.

Brief Description of the Drawings:

Fig. 1 is a block diagram of a PLL circuit according to the invention;

Fig. 2 is a block diagram of a PLL frequency synthesis circuit; and

Fig. 3 is a schematic illustration of a time slot structure used in a data transmission system, and the timings of operating states of the PLL frequency synthesis circuit within the time slot structure.

Description of the Preferred Embodiments:

Referring now to the figures of the drawing in detail and first, particularly, to Fig. 1 thereof, there is shown a basic configuration of a PLL circuit. The PLL circuit has a phase detector PFD (Phase Frequency Detector), a loop filter LF and a voltage controlled oscillator VCO. The VCO produces a periodic oscillation  $y(t)$  which is fed back via a feedback line FBL (Feedback Loop) to a first input of the phase



detector PFD. A second input of the phase detector PFD is supplied with a reference variable  $x(t)$  in the form of an oscillation. A variable  $t$  denotes the time.

5 The object of the PLL circuit is to allow the time response of the output variable  $y(t)$  to follow the input variable  $x(t)$ . In other words, the frequency of the voltage controlled oscillator VCO should be set such that it matches the frequency of the oscillation  $x(t)$ . To do this, the phase of  
10 the output signal  $y(t)$  is compared with the phase of the reference variable  $x(t)$ . The phase detector PFD outputs an output signal that represents a measure of the determined phase difference between the two variables. After low-pass filtering, the phase difference signal is used in the loop  
15 filter LF to control the oscillator VCO. The loop filter LF smoothes the phase difference signal.

Owing to the inertia of the control system, the output variable  $y(t)$  cannot immediately follow a sudden change in the  
20 reference variable  $x(t)$ . The time which is required to reduce the frequency error between  $x(t)$  and  $y(t)$  to a desired level is referred to as the settle time, and will be considered in more detail in the following text.

25 The control principle explained with reference to Fig. 1 is used in a PLL frequency synthesizer. PLL frequency

synthesizers are used in data transmission devices. Their object is to generate a desired carrier frequency  $F_{out}$  from a constant reference frequency  $F_{ref}$ , with the carrier frequency  $F_{out}$  being several orders of magnitude above the reference frequency. The capability of the PLL frequency synthesizer to change between different output frequencies  $F_{out}$  as quickly as possible is of major importance in this case. Rapid changes between different output frequencies (user channels) are of particular importance for data transmission devices for mobile and/or cordless telephony since, in these applications, a large number of user channels and the FH method are regularly used.

Transmission standards such as DECT or - recently - Bluetooth have been developed for data transmission systems such as these, and these standards are based on frequency hopping (FH). In the case of FH, each logical channel (that is to say subscriber) is allocated a physical channel (that is to say a specific user frequency) for only a specific, short time. Once this time has elapsed, a frequency change must be carried out. Therefore, the transmission frequency (and reception frequency) are changed continually throughout transmission operation (and reception operation).

Fig. 2 shows a block diagram of a PLL frequency synthesizer that is suitable for carrying out the method according to the

invention. The PLL frequency synthesizer has a PLL circuit as shown in Fig. 1, in whose feedback line FBL a programmable frequency divider DIV is provided. The programmable frequency divider DIV is supplied with a control signal C, which  
5 indicates to the frequency divider DIV that it should carry out a frequency division by the division factor  $1/N$ . Different output frequencies  $F_{out}$  are then produced by repeatedly reprogramming the frequency divider DIV.

10 In the case of DECT, the carrier frequencies are in a frequency band between 1880 and 1900 MHz. The constant reference frequency  $F_{ref}$  is derived from a crystal oscillator and is, for example, 5 MHz. In consequence, in the case of DECT, frequency division is carried out in the range between  
15  $1/376$  and  $1/380$  ( $N$  may in this case also not be an integer or, in order to achieve suitable frequency division, a further frequency divider (not shown) with a fixed division ratio may be disposed between the crystal oscillator and the phase detector PFD).

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As already mentioned, the VCO is the element that produces the oscillation for the PLL frequency synthesizer. The output frequency  $F_{out}$  from the VCO is obtained, in the simplest case, from a linear function in accordance with the following

25 equation:

$$F_{out} = F_{free} + K_{vco} \times V_c.$$

In this case,  $F_{free}$  is the frequency of the free-running oscillator VCO,  $K_{vco}$  is the voltage/frequency "gain" of the oscillator VCO, and  $V_c$  is the control voltage which influences the output frequency  $F_{out}$  of the oscillator VCO.

In the case of a TDMA data transmission system, the data is transmitted in portions, in what are referred to as bursts or else data packets. For the sake of simplicity, the following text generally uses the expression data bursts, even when data packets are meant.

Depending on the data transmission system under consideration, either two or more data bursts or (a maximum of) one data burst are or is transmitted in one TDMA time slot. In the case of packet transmission, it is also possible for the transmission of one data packet to extend over two or more time slots. The FH times are likewise controlled differently depending on the standard under consideration. For example, in the Bluetooth Standard, two frequency hops can occur, and two data packets can be transmitted, in one time slot with a length of 625  $\mu s$ . The FH frequency change times and the TDMA time slot structure are, however, always matched to one another in time, that is to say they are commensurable. In many cases, short PLL settle times are therefore extremely

helpful, for example in order to make it possible to optimally use a predetermined time slot structure for a predetermined burst length, or in order to make it possible still to achieve a predetermined minimum FH hopping frequency rate with a  
5 predetermined burst length.

This will be explained in the following text with reference to an example.

10 Fig. 3 shows two successive time slots Z1 and Z2. The time slot Z1 starts at  $t_0$  and lasts until  $t_2$ , and the second time slot Z2 starts at  $t_2$  and lasts until  $t_4$ .

Both time slots Z1 and Z2 are used for data transmission. A  
15 first burst P1 is transmitted in a time interval from  $t_0$  to  $t_1$  in the time slot Z1. No data transmission takes place in the time interval from  $t_1$  to  $t_2$ , whose length is  $\tau$ . A second data burst P2 is transmitted in the time interval from  $t_2$  to  $t_3$ . The remaining time interval  $t_3$  to  $t_4$ , with the length  $\tau$  of the  
20 second time slot Z2, once again has no data transmission activity.

In the example, it is assumed that the first data burst P1 is transmitted at a frequency  $F_{out1}$ , and that a different  
25 frequency  $F_{out2}$  is provided for transmitting the second data burst. Therefore, the PLL frequency synthesizer illustrated

in Fig. 2 must change from the first output frequency  $F_{out1}$  to the second output frequency  $F_{out2}$  in order to transmit the second data burst P2.

5 In the conventional method, the PLL synthesizer is for this purpose switched off after each transmission of a data burst P1, P2, that is to say at the times  $t_1$  and  $t_3$ . The reason for switching it off is to save power during the time periods  $t_1$  to  $t_2$  and  $t_3$  to  $t_4$ , in which no data transmission activity  
10 takes place. Once the PLL frequency synthesizer has been switched off, the programmable frequency divider DIV is then reprogrammed to the desired value for the second output frequency  $F_{out2}$ , and the PLL frequency synthesizer is activated once again.

15 Provided that  $\tau$  is sufficiently long, no problems occur during this process. However, difficulties occur for short times of  $\tau$ .

20 This is because, when the oscillator VCO is switched on once again, it first starts to oscillate at the free-running frequency  $F_{free}$ . The free-running frequency  $F_{free}$  cannot be set exactly, owing to manufacturing tolerances. A situation therefore occurs in practice in which the free-running  
25 frequency  $F_{free}$  is not located within the intended FDMA frequency band. In this situation, the control delay for the

PLL lengthens the overall time that is required for the stabilization process from the deactivated state to the desired output frequency Fout2.

- 5 In order to make it possible to carry out a frequency change in a shorter time, the invention provides for the voltage controlled oscillator VCO not to be deactivated after handling the previous data burst P1 but to be set to a different suitable frequency in the frequency band, in particular to its  
10 mid-frequency, and to be reprogrammed from there to the desired frequency Fout2. The stabilization process then takes place from Fout1 via the suitable frequency to Fout2, and is faster than in the case of conventional methods.
- 15 Particularly in situations where the intended frequency Fout2 is not yet known at the time t1, the method according to the invention makes it possible to change to the second output frequency Fout2 in a very short time, as soon as the new frequency information is provided for the PLL frequency  
20 synthesizer.

It should be mentioned that the invention makes it possible to increase the information transmission rate in certain circumstances. This is the situation when, in the case of a  
25 conventional procedure (deactivation of the VCO after each data burst transmission), the remaining time  $\tau$  before the

start of the next time slot Z2 is no longer sufficient, with correspondingly short dimensioning of the time slot structure, for the PLL frequency synthesizer to be stabilized (output frequency:  $F_{out2}$ ) by the time  $t_2$ . In this situation, the data burst P2 cannot be transmitted in the time slot Z2, and the transmission of the data burst P2 must be delayed to the next time slot Z3, or to an even later time slot. The shortening of the settle time which is achieved by the method according to the invention makes it possible in a situation such as this for the stabilization process possibly still to be completed in good time at the time  $t_2$ , so that the data burst P2 is still transmitted in the second time slot Z2. To this extent, it is also possible to provide for the method according to the invention to be used as the operating mode only at times, namely when a high data rate is required, and in other cases to operate the PLL in the conventional operating mode, with the PLL being switched off between activity periods.